



Friday 14 June 2024 – Afternoon

A Level Further Mathematics A

Y543/01 Mechanics

Time allowed: 41 hour 30 minutes 30494 34049 hour 30 minutes 30,4049 340494

You must have:

- the Printed Answer Booklet
- the Formulae Booklet for A Level Further Mathematics A
- a scientific or graphical calculator



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INSTRUCTIONS

- Use black ink. You can use an HB pencil, but only for graphs and diagrams.
- Write your answer to each question in the space provided in the **Printed Answer** Booklet. If you need extra space use the lined pages at the end of the Printed Answer Booklet. The question numbers must be clearly shown.
- Fill in the boxes on the front of the Printed Answer Booklet.
- Answer all the questions.
- · Where appropriate, your answer should be supported with working. Marks might be given for using a correct method, even if your answer is wrong.
- Give non-exact numerical answers correct to 3 significant figures unless a different degree of accuracy is specified in the question.
- The acceleration due to gravity is denoted by gm s⁻². When a numerical value is needed use g = 9.8 unless a different value is specified in the question.
- Do not send this Question Paper for marking. Keep in the centre or recycle it.

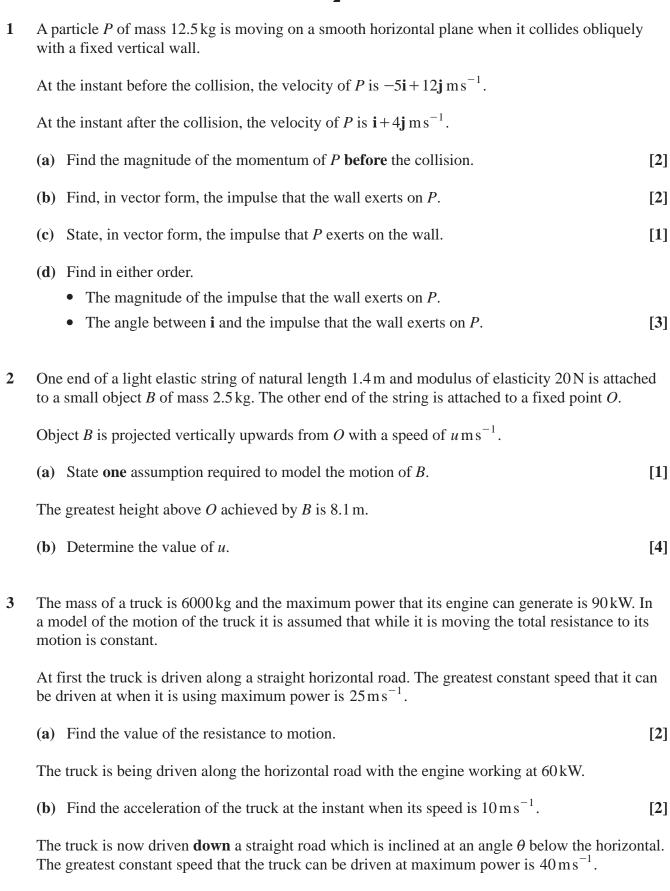
INFORMATION

- The total mark for this paper is 75.
- The marks for each question are shown in brackets [].
- This document has 8 pages.

ADVICE

Read each question carefully before you start your answer.

[3]

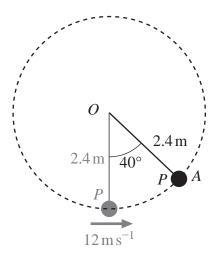


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(c) Determine the value of θ .

4 A particle, *P*, of mass 6kg is attached to one end of a light inextensible rod of length 2.4 m. The other end of the rod is smoothly hinged at a fixed point *O* and the rod is free to rotate in any direction.

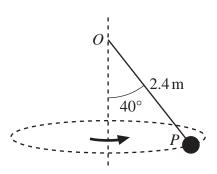
Initially, P is at rest, vertically below O, when it is projected horizontally with a speed of $12 \,\mathrm{m\,s}^{-1}$. It subsequently describes complete vertical circles with O as the centre.



The angle that the rod makes with the downward vertical through O at each instant is denoted by θ and A is the point which P passes through where $\theta = 40^{\circ}$ (see diagram).

- (a) Find the tangential acceleration of *P* at *A*, stating its direction. [2]
- (b) Determine the radial acceleration of *P* at *A*, stating its direction. [6]
- (c) Find the magnitude of the force in the rod when *P* is at *A*, stating whether the rod is in tension or compression. [2]

The motion is now stopped when P is at A, and P is then projected in such a way that it now describes horizontal circles at a constant speed with $\theta = 40^{\circ}$ (see diagram).



- (d) Find the speed of *P*. [4]
- (e) Explain why, wherever P's motion is initiated from and whatever its initial velocity, it is **not** possible for P to describe horizontal circles at constant speed with $\theta = 90^{\circ}$. [1]

5 In this question you may assume that if x and y are any physical quantities then $\left[\frac{dy}{dx}\right] = \left[\frac{y}{x}\right]$.

A machine drives a piston of mass m into a vertical cylinder. The equation below is suggested to model the power developed by the machine, P, while it is not doing any other external work.

$$P = k_1 m v \frac{\mathrm{d}v}{\mathrm{d}t} + k_2 m g v + k_3 E$$

in which

- v is the velocity of the piston at a given time,
- g is the acceleration due to gravity,
- E is the **rate** at which heat energy is lost to the surroundings,
- k_1 , k_2 and k_3 are dimensionless constants.

Determine whether the equation is dimensionally consistent. Show all the steps in your argument.

[6]

- - (a) By finding, in terms of e, an expression for the velocity of B after the collision, show that the direction of motion of B is reversed by the collision. [5]

After the collision between A and B, which is **not** perfectly elastic, B goes on to collide directly with a fixed, vertical wall. The coefficient of restitution between B and the wall is $\frac{2}{5}e$. After the collision between B and the wall, there are no further collisions between A and B.

(b) Determine the range of possible values of *e*. [7]

A body B of mass 1.5 kg is moving along the x-axis. At the instant that it is at the origin, O, its velocity is $u \,\mathrm{m\,s}^{-1}$ in the positive x-direction.

At any instant, the resistance to the motion of B is modelled as being directly proportional to v^2 where $v \, \text{m s}^{-1}$ is the velocity of B at that instant. The resistance to motion is the only horizontal force acting on B.

At an instant when B's velocity is $2 \,\mathrm{m\,s}^{-1}$, the resistance to its motion is 24 N.

- (a) Show that B's motion can be modelled by the differential equation $\frac{1}{v} \frac{dv}{dx} = -4$. [3]
- (b) (i) Solve the differential equation in part (a) to find the particular solution for v in terms of x and u.
 - (ii) By considering the behaviour of v as $x \to \infty$ describe **one** feature of the model that is not realistic. [1]

At the instant when B reaches the point A, where x = X, its speed is $V \, \text{m s}^{-1}$. The work done by the resistance as B moves from O to A is denoted by WJ.

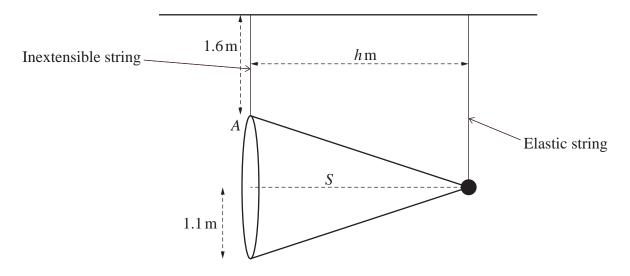
- (c) (i) Use the formula $W = \int F dx$ to determine an expression for W in terms of X and u. [3]
 - (ii) Explain the relevance of the sign of your answer in part (c)(i). [1]
 - (iii) By writing your answer to part (c)(i) in terms of V and u show how the quantity W relates to the energy of B. [2]

[7]

- 8 A shape, S, is formed by attaching a particle of mass $2m \log n$ to the vertex of a uniform solid cone of mass $8m \log n$. The height of the cone is $h \log n$ and the radius of the base of the cone is $1.1 \log n$.
 - (a) Explain why the centre of mass of S must lie on the central axis of the cone. [1]

Two strings are attached to *S*, one at the vertex of the cone and one at *A* which is a point on the edge of the base of *S*. The other ends of the strings are attached to a horizontal ceiling in such a way that the strings are both vertical. The string attached to *S* at *A* is inextensible and has length 1.6 m. The string attached to *S* at the vertex is elastic with modulus of elasticity 8 mg N.

Shape *S* is in equilibrium with its axis horizontal (see diagram).



(b) Determine the natural length of the elastic string.

END OF QUESTION PAPER

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